

21.0 Ergodicity

21.1 Ergodic in Mean

Definition: The WSS RP $X(t)$ is said to be *ergodic in mean* if

$$\mu_T = \frac{1}{2T} \int_{-T}^T X(t) dt \rightarrow \mu_X \text{ in M.S. as } T \rightarrow \infty.$$

$$E[\mu_T] = \frac{1}{2T} \int_{-T}^T E[X(t)] dt = \mu_x$$

so μ_T is an unbiased estimator for μ_X .

$$Var[\mu_T] = \left(\frac{1}{2T}\right)^2 \int_{-T}^T \int_{-T}^T K_X(t_1 - t_2) dt_1 dt_2.$$

The WSS random process $X(t)$ is ergodic in mean if and only if

$$\lim_{T \rightarrow \infty} \left(\frac{1}{2T}\right)^2 \int_{-T}^T \int_{-T}^T K_X(t_1 - t_2) dt_1 dt_2 = 0.$$

By letting $s = t_1 + t_2$ and $\tau = t_1 - t_2$ we can write

$$Var[\mu_T] = \left(\frac{1}{2T}\right)^2 \int_{-2T}^{2T} \int_{-2T-|\tau|}^{2T-|\tau|} K_X(\tau) ds d\tau.$$

Simplifying this expression leads to the following theorem:

Theorem: A WSS random process $X(t)$ is ergodic in the mean if and only if

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-2T}^{2T} K_X(\tau) \left[1 - \frac{|\tau|}{2T}\right] d\tau = 0.$$

Proposition: The WSS RP $X(t)$ is ergodic in mean if

$$\int_{-\infty}^{\infty} |K_X(\tau)| dt < \infty.$$

Proof: Note that

$$1 - \frac{|\tau|}{2T} \leq 1 \text{ for } -2T \leq \tau \leq 2T.$$

Thus

$$\text{Var}[\mu_T] \leq \frac{1}{2T} \int_{-2T}^{2T} |K_X(\tau)| d\tau \rightarrow 0 \text{ as } T \rightarrow \infty.$$

Proposition: The WSS RP $X(t)$ is ergodic in mean if

$$\lim_{\tau \rightarrow \infty} |K_X(\tau)| = 0.$$

Proof: Let

$$K_m = \max_{\tau} \{K_X(\tau)\}.$$

Let $\delta > 0$. Then there exists M such that $|K_X(\tau)| \leq \delta$ for $|\tau| \geq M$. So

$$\begin{aligned} \text{Var}(\mu_T) &\leq \frac{1}{2T} \int_{-2T}^{2T} |K_X(\tau)| d\tau \\ &\leq \frac{1}{2T} \left[\int_{-M}^M K_m d\tau + \int_{-2T}^{-M} \delta d\tau + \int_M^{2T} \delta d\tau \right] \end{aligned}$$

(we make $T > M$)

$$\begin{aligned} &= \frac{1}{2T} [2MK_m + (4T - 2M)\delta] \\ &\leq \frac{M}{T} K_m + 2\delta. \end{aligned}$$

For any $\epsilon > 0$ let

$$\delta = \frac{1}{2} \left[\epsilon - \frac{M}{T} K_m \right].$$

$\delta > 0$ as $T \rightarrow \infty$. Here

$$\text{Var}(\mu_T) \leq \epsilon.$$

Since ϵ is arbitrary, $\text{Var}(\mu_T) \rightarrow 0$.

21.2 Ergodic in Correlation

Definition: The WSS RP $X(t)$ is said to be *ergodic in correlation at shift* λ if

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T X(t + \lambda) X(t) dt = R_X(\lambda) \text{ (M.S.)}.$$

If this holds for all λ we say $X(t)$ is *ergodic in correlation*.

Let

$$\phi_\lambda(t) = X(t + \tau) X(t).$$

Theorem: The WSS RP $X(t)$ is ergodic in correlation if and only if

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-2T}^{2T} K_{\phi_\lambda}(\tau) \left[1 - \frac{|\tau|}{2T} \right] d\tau = 0.$$

Proof: The proof is the same as proving ergodic in mean for $\phi_\lambda(t)$.

21.3 Ergodic in Mean Square

Definition: The WSS RP $X(t)$ is said to be *ergodic in mean square* if

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T X^2(t) dt = R_X(0) \text{ (M.S.)}.$$

Example: Let

$$X(t) = A \cos[2\pi f_0 t + \theta]$$

where $A \sim N(0, 1)$, $\theta \sim U[-\pi, \pi]$. Then

$$E[X(t)] = 0.$$

$$K_X(t + \tau, t) = E[X(t + \tau)X(t)] = \frac{1}{2\pi} \cos(2\pi f_0 \tau)$$

which implies $X(t)$ is WSS.

Is $X(t)$ ergodic in mean? Note that

$$\int_{-\infty}^{\infty} |K_X(\tau)| d\tau = \infty$$

so we need to check the more strict condition

$$Var(\mu_T) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-2T}^{2T} \left(1 - \frac{|\tau|}{2T} \right) \frac{1}{2} \cos(2\pi f_0 \tau) d\tau.$$

Define

$$tri(2T) = \left(1 - \frac{|\tau|}{2T} \right).$$

Then $tri(2T)$ is the convolution of two rectangles each with height $1/2T$ from $-T$ to T . Hence

$$Var(\mu_T) = \lim_{T \rightarrow \infty} \frac{1}{4T} Re \left\{ \int_{-\infty}^{\infty} tri(2T) \exp(-i2\pi f_0 \tau) d\tau \right\}$$

$$= \frac{1}{4T} \text{Re} \{ F[\text{tri}(2T)|_{f=f_0}] \}$$

where F denotes a Fourier transform. Now the Fourier transform of $\text{tri}(2T)$ is

$$2T \left(\frac{\sin 2\pi fT}{2\pi fT} \right)^2$$

so $\text{Var}(\mu_T) \rightarrow 0$ as $T \rightarrow \infty$. Therefore $X(t)$ is ergodic in mean.

Is $X(t)$ ergodic in M.S.?

$$\begin{aligned} \frac{1}{2T} \int_{-T}^T X^2(t) dt &= \frac{1}{2T} \int_{-T}^T A^2 \cos^2(2\pi f_0 t + \theta) dt \\ &= \frac{A^2}{2T} \int_{-T}^T \cos^2(2\pi f_0 t + \theta) dt \end{aligned}$$

which yields a different result for different A since A is random. Hence $X(t)$ is not ergodic in M.S. and so is not ergodic in correlation either.

21.4 Ergodic in Distribution

Suppose $X(t)$ is stationary in first and second order distributions. Then

$$F_X(x; t) = P[X(u, t) \leq x] = F_X(x; 0) \quad \forall t \in T,$$

$$F_X(x_1, x_2; t_1, t_2) = F_X(x_1, x_2; t_1 + \tau, t_2 + \tau) \quad \forall t_1, t_2, \tau \in T.$$

Here we estimate $F_X(x; 0)$ from a single sample function. Let

$$I_x(t) = \begin{cases} 1, & X(t) \leq x, \\ 0, & \text{elsewhere.} \end{cases}$$

$I_x(t)$ is the indicator function. Let

$$\hat{F}_X(x) = \frac{1}{2T} \int_{-T}^T I_x(t) dt.$$

Then

$$E[\hat{F}_X(x)] = E\left[\frac{1}{2T} \int_{-T}^T I_x(t) dt\right] = \frac{1}{2T} \int_{-T}^T E[I_x(t)] dt.$$

Now

$$E[I_x(t)] = P[X(t) \leq x] = F_X(x; t) = F_X(x; 0)$$

where the last equality follows from first order stationarity. Thus

$$E[\hat{F}_X(x)] = F_X(x; 0).$$

Now consider

$$\begin{aligned} E[I_x(t_1)I_x(t_2)] &= P[X(t_1) \leq x, X(t_2) \leq x] \\ &= F_X(x, x; t_1, t_2) = F_X(x, x; t_1 - t_2, 0). \end{aligned}$$

So $I_x(t)$ will be a WSS RP provided $X(t)$ is stationary of order 2. Applying our previous theorem we get the following theorem.

Theorem: The WSS RP $X(t)$ which is stationary up to order 2 is ergodic in distribution if and only if

$$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T K_{I_x}(\tau) \left[1 - \frac{|\tau|}{2T}\right] d\tau = 0$$

where

$$\begin{aligned} K_{I_x}(\tau) &= E[(I_x(t) - E[I_x(t)])(I_x(t - \tau) - E[I_x(t - \tau)])] \\ &= F_X(x, x; \tau) - F_X^2(x). \end{aligned}$$